

# Muhammad Bilal Shahid

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## Summary

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PhD researcher in Mechanical Engineering with a minor in Computer Engineering, specializing in dynamical systems, time-series forecasting, and uncertainty-aware machine learning. Developed Predictor-Corrector frameworks using Neural CDE & Modern Hopfield Networks for correction & correction/calibration of learned time-series models, respectively. Skilled in Python, PyTorch, Jax, & HPC workflows.

## Education

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<b>PhD Mechanical Engineering - Iowa State University</b>	Jan 2021 – Present
• <b>Minor:</b> Computer Engineering	<b>CGPA: 3.67/4.00</b>
<b>MS Mechanical Engineering - Incheon National University</b>	Jan 2018 – Feb 2020
<b>BS - GIK Institute of Engineering Sciences &amp; Technology</b>	Aug 2012 – May 2016

## Experience

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<b>PhD Researcher in Dynamical Systems and Forecasting - Iowa State University</b>	Jan 2021 – Present
• Introduced a Corrector to correct forecasts of the learned time-series models	
• Developed an approach to generate calibrated and sharp prediction intervals for forecasting	
• Target variable selection for robust car following dynamics modeling via Blackbox models	
<b>MS Researcher in ML &amp; Manufacturing - Incheon National University</b>	Jan 2018 – Jul 2020
• Worked on integrating Machine learning and Ultrasonic Welding	
• Developed a Machine learning based approach to assist with Ultrasonic Weld Horn Design	
• Developed a set of weld attributes for sound quality joints via nanoindentation & optical microscopy	
<b>Intern - Fauji Fertilizer Company</b>	Jan 2018 – Jul 2020
• Worked on the maintenance of boilers, heat exchangers, and cooling towers	

## Research Projects [[github.com/mbelalsh](https://github.com/mbelalsh)]

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<b>Correctors for learned time-series models</b>	Paper   Code
• Introduced a Predictor-Corrector framework for learned time-series models	
• The Corrector, based on Neural CDE, can correct any learned time-series model	
• Obtained state-of-the-art results on forecasting benchmarks	
<b>Calibration of Dynamics Models via Pattern Retrieval</b>	Paper   Code
• Developed an algorithm to generate calibrated forecasts of system dynamics based on pattern retrieval	
• Introduced a Predictor-Corrector framework, where the Corrector was based on Modern Hopfield Networks	
• The Corrector corrects the Predictor as well as generates prediction intervals	
<b>Robust Car Following Dynamics Modeling</b>	Paper   Code
• Focused on target variable selection to train Blackbox models for robust car following dynamics modeling	
• The paper concludes with the best choices of the target variable for different types of Blackbox models	
<b>Uncertainty-aware Hybrid Crop Model</b>	Code
• Developed a Neural-Mechanistic model that generates calibrated prediction intervals for key plant state variables	
• The algorithm has applications in sensor placement optimization and precision agriculture.	

## Skills

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**Programming:** Python, Jax, PyTorch, Numpy, Matplotlib, Github,  $\LaTeX$ , Linux,

**Deep Learning:** Supervised Learning, Unsupervised Learning, Uncertainty Quantification, Pattern Retrieval

**Time Series:** Time Series Forecasting, Dynamics Modeling, Autoregressive Models,